

The role of M-matrices in the study of nonlinear operator systems via monotone operators methods

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In the talk I will study a system of equations of the form

$$\begin{cases} -\operatorname{div}(\varphi_1(x, \|\nabla u(x)\|) \nabla u(x)) + \langle \mathbf{a} | \nabla u(x) \rangle = f_1(x, u(x), w(x)) & \text{for } x \in \Omega, \\ -\operatorname{div}(\varphi_2(x, \|\nabla w(x)\|) \nabla w(x)) + \langle \mathbf{b} | \nabla w(x) \rangle = f_2(x, u(x), w(x)) & \text{for } x \in \Omega, \\ u(x) = w(x) = 0 & \text{for } x \in \partial\Omega. \end{cases} \quad (1)$$

and present conditions that guarantee the existence of solutions of the system (1) that are also (in a particular, potential case, when $\mathbf{a} = \mathbf{b} = \mathbf{0}$) Nash-type equilibrium for functionals

$$\begin{aligned} E_1(u, w) &= \int_{\Omega} \int_0^{\|\nabla u(x)\|} \varphi_1(x, s) s \, ds dx - \int_{\Omega} \int_0^{u(x)} f(x, s, w(x)) \, ds dx, \\ E_2(u, w) &= \int_{\Omega} \int_0^{\|\nabla w(x)\|} \varphi_2(x, s) s \, ds dx - \int_{\Omega} \int_0^{w(x)} f(x, u(x), s) \, ds dx, \\ &\text{for all } u, w \in H_0^1(\Omega) \end{aligned}$$

An investigation into the existence of such solutions, started in [4], was continued for instance in [3, 5]. All the works mentioned were based on Perov's Contraposition Principle theorem and on Ekeland's Variational Principle or on other variational techniques. Presented approach, using M-matrices and the Theory of Monotone Operators, develops our earlier results, see [1, 2].

References

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